

The **5**th **RoboCup Middle Size League International Workshop** will be held in November 2015, in Aveiro, Portugal. Teams from the Middle Size League, as well as other RoboCup leagues, are herein invited to join and actively participate in this workshop that will try follow up the success of the previous editions.



Aveiro is a small city near the North coast of Portugal. Its University, with only 43 years of age, is concentrated in a single university campus with excellent conditions and a very pleasant and cozy space distribution. Despite not being a Technical University, Aveiro's University has a high international reputation in the engineering fields, namely in the areas of materials, mechanics, electronics, and telecommunications.

The IRIS Lab (Intelligent Systems and Intelligent Robotics lab) is part of the research institute IEETA/DETI (Institute of Electronics and Informatics Engineering of Aveiro). Being a small

robotics lab when compared to other world wide well known labs, it has a solid and productive team that has been able to produce excellent research results in several application areas of mobile and anthropocentric robotics.

The Workshop will take place during the European Robotics Week, giving a special meaning to its involvement in the robotics research efforts.



Further information will be released in the near by months. The workshop site will be regularly updated with new information, namely: period for workshop registration (free), final schedule, accommodations in Aveiro, touristic sites and so on.

Tentative schedule

	Monday 23 / Nov	Tuesday 24 / Nov	Wednesday 25 / Nov
9 - 10			
10 - 11		Hands-on	Wrap-up
11 - 12		Session	wrap-up
12 - 13	Reception		
13 - 14	Lunch	Lunch	Lunch
14 - 15			
15 - 16	Presentations	Hands-on Session	
16 - 17			
17 - 18			
18 - 19	Social Event		
19 - 20		Free Time	
20 - 21			
21 - 22			

More info at:

http://wiki.robocup.org/images/7/72/The 5th RoboCup Middle Size League International Workshop.pdf#

Contacts: mbc@det.ua.pt; cambada@ua.pt; jla@ua.pt